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TOP code
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Numerical approach
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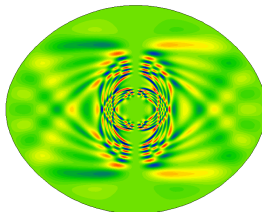
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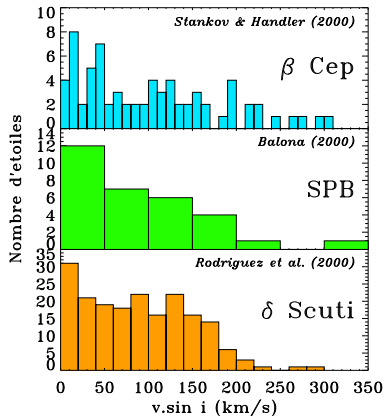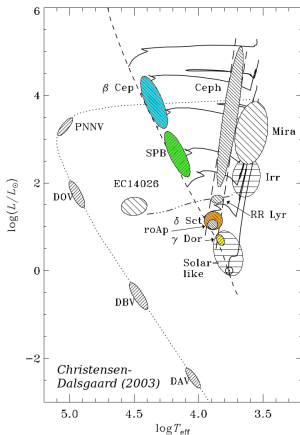# 2D oscillation computations in rapidly rotating stars with the TOP code

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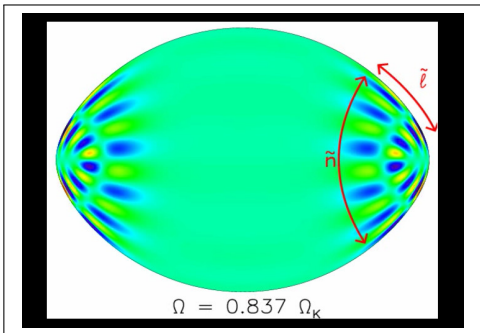November 29, 2018

Scientific context

- seismic interpretation of rapidly rotating stars
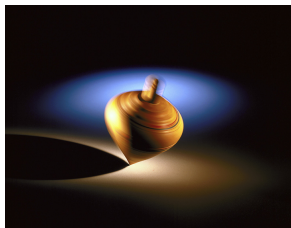
Scientific context

Effects of rapid rotation

- centrifugal deformation
- Coriolis force
- significant distortion of pulsation modes
- need for a 2D numerical approach

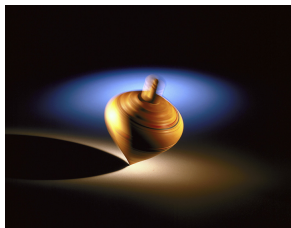$\Omega = 0.837\ \Omega_K$

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The TOP code

- TOP = Two-dimensional Oscillation Program
- top = "toupie" (in French)

http://johnmannophoto.com/blog/?p=103

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The TOP code

- TOP = Two-dimensional Oscillation Program
- top = "toupie" (in French)

http://johnmannophoto.com/blog/?p=103

- initially started writing the code in 2007-2009 during first postdoc in Sheffield
  - numerical method based on Lignières et al. (2006)
  - borrowed parts from LSB (= Linear Solver-Builder)
- multi-domain version 2010-2011 (with J. Ballot)
- non-adiabatic version 2012-2013 (with M.-A. Dupret)
- B. Putigny unified multiple versions, added a python interface, and started redoing the script language (∼2013-present)

The TOP code

Basic characteristics

- Fortran 90 code
- Perl code for interpreting pulsation equations in script file
    - this produces Fortran code, prior to compilation
    - may be replaced by a newer interpreter in C++ & other language

Script file with equations

Pre-processing

Fortran source code

Compilation

Executable program

The TOP code

Current script

New script

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The TOP code

Numerical aspects and parallelisation

- TOP relies on BLAS and LAPACK for most of the heavy computations
  - good optimisation on most (super-)computers
  - provides OpenMP type parallelisation
- experimented with ScaLAPACK library
  - provides MPI type parallelisation
  - may allow solving 3D problems (by increasing available RAM)

Numerical approach

- 2D numerical approach
- Angular discretisation: spherical harmonic
- Radial discretisation:
  - polytrope: Chebyshev
  - realistic model: FD or splines
- Uses a suitable coordinate system (ζ, θ, ϕ) (cf. Bonazzola et al., 1998)

$$[\text{System of equations}] \Rightarrow Av = \lambda Bv$$

Method

1. Find explicit equations in spheroidal coordinates

Continuity equation
Euler's equation
Adiabatic relation
Poisson's equation

Method

1. Find explicit equations in spheroidal coordinates

2. Express unknowns using spherical harmonics

For example: $\Phi(\zeta, \theta, \varphi) = \sum_{\ell=|m|}^{\ell_{max}} \Phi_m^\ell(\zeta) Y_\ell^m(\theta, \varphi)$

Method

1. Find explicit equations in spheroidal coordinates

3. Project equations on spherical harmonic basis

2. Express unknowns using spherical harmonics

For example: $\qquad \iint_{4\pi} \{Y_\ell^m\}^* \{\text{Continuity equation}\} \, d\Omega$

Method

1. Find explicit equations in spheroidal coordinates

3. Project equations on spherical harmonic basis

2. Express unknowns using spherical harmonics

4. Carry out radial discretisation (Chebyshev, FD, splines)

Generalised eigenvalue problem: $Av = \lambda Bv$

Horizontal discretisation

Only Coriolis   **Centrifugal def.**   **Equat. symmetry**

- spectral convergence with spherical harmonics
- problem couples all spherical harmonics of same parity

Radial discretisation

FD/spline derivation matrix   Chebyshev derivation matrix

Discretisation	Convergence	Grid
FD/splines	algebraic	flexible
Chebyshev polynomials	exponential	fixed

Radial discretisation – Chebyshev polynomials

Characteristics

- construct & factorise full matrix

  - good parallelisation

Illustration

- **Model**: polytrope
- **Resolution**: 5670×5670
  - $N_r = 81$
  - $N_\theta = 10$
- **Fill factor**: 10.6%

Matrix

Radial discretisation – Chebyshev polynomials

Characteristics

- construct & factorise band matrix
  - poor parallelisation

Illustration

- **Model**: SCF
- **Resolution**: 8080×8080
  - $(N_r, N_\theta) = (101, 10)$
  - Lower bands: 130
  - Upper bands: 140
- **Fill factor**: 27.0 %

Matrix

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Matrix construction

- the order of the equations and the variables are set by the user
  - when dealing with FD/splines, group ℓ values together to obtain banded matrix
  - fine-tune ordering to reduce number of bands

Solving the eigenvalue problem

Arnoldi-Chebyshev algorithm

- iterative procedure in which original matrix is approximated by a smaller matrix obtained by successive iterations of: Av

  starting with some initial vector v_0

Solving the eigenvalue problem

Arnoldi-Chebyshev algorithm

- iterative procedure in which original matrix is approximated by a smaller matrix obtained by successive iterations of: Av

  starting with some initial vector v_0

Spectral transformation

$$Av = \lambda Bv \iff (A - \sigma B)^{-1} Bv = \mu v \qquad \text{where} \qquad \lambda = \sigma + \frac{1}{\mu}$$

- when targeting eigenvalues close to σ, we need to solve $(A - \sigma B) X = Y$

- it is therefore necessary to construct and factorise $A - \sigma B$

Polynomial eigenvalue problem

$$\sum_{i=0}^{n} \lambda^i A_i v = 0 \qquad \Longleftrightarrow \qquad \mathcal{A}x = \lambda \mathcal{B}x \qquad \text{where}$$

$$\mathcal{A} = \left[\begin{array}{cccc} A_0 & \cdot & \cdot & \cdot \\ \cdot & I_{\mathrm{d}} & \cdot & \cdot \\ \cdot & \cdot & \ddots & \cdot \\ \cdot & \cdot & \cdot & I_{\mathrm{d}} \end{array}\right], \quad \mathcal{B} = \left[\begin{array}{cccc} -A_1 & -A_2 & \cdots & -A_n \\ I_{\mathrm{d}} & \cdot & \cdot & \cdot \\ \cdot & \ddots & \cdot & \cdot \\ \cdot & \cdot & I_{\mathrm{d}} & \cdot \end{array}\right], \quad x = \left[\begin{array}{c} v \\ \lambda v \\ \vdots \\ \lambda^{n-1} v \end{array}\right]$$

Solving $(\mathcal{A} - \sigma \mathcal{B})X = Y$

1. $X = [x_0 \dots x_{n-1}]^T, \qquad Y = [y_0 \dots y_{n-1}]^T$

2. By induction, let us define $(w_i)_{i \in [1, n-1]}$:
   $w_1 = \sigma y_1, \qquad w_{i+1} = \sigma(y_{i+1} + w_i)$

3. Solve: $x_0 = \left(\sum_{i=0}^{n} \sigma^i A_i\right)^{-1} \left(y_0 - \sum_{i=1}^{n-1} A_{i+1} w_i\right)$

4. By induction: $x_{i+1} = y_{i+1} + \sigma x_i$

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The multi-domain approach

- **assumption**: only consecutive domains are coupled
  - ⇒ tridiagonal block matrix

$$
\begin{bmatrix}
A_{11} & A_{12} & & \\
A_{21} & A_{22} & A_{23} & \\
& \ddots & & A_{n-1,\,n} \\
& & A_{n,\,n-1} & A_{n,\,n}
\end{bmatrix}
\begin{bmatrix}
X_1 \\
X_2 \\
\vdots \\
X_n
\end{bmatrix}
=
\begin{bmatrix}
Y_1 \\
Y_2 \\
\vdots \\
Y_n
\end{bmatrix}
$$

Solving this system

- use of Gauss' pivot to eliminate $A_{i+1,\,i}$ and $A_{i,\,i+1}$
- one should not forget that matrix multiplication is not commutative

"Factorisation"

$$\tilde{A}_{11} = A_{11} \qquad \tilde{A}_{i+1,\,i+1} = A_{i+1,\,i+1} - A_{i+1,\,i}\tilde{A}_{i,\,i}^{-1}A_{i,\,i+1}$$

Downward sweep

$$\tilde{Y}_1 = Y_1 \qquad \tilde{Y}_{i+1} = Y_{i+1} - A_{i+1,\,i}\tilde{A}_{i,\,i}^{-1}\tilde{Y}_i$$

Upward sweep

$$X_n = \tilde{A}_{n,\,n}^{-1}\tilde{Y}_n \qquad X_{i-1} = \tilde{A}_{i-1,\,i-1}^{-1}\left(\tilde{Y}_{i-1} - A_{i-1,\,i}\tilde{X}_i\right)$$

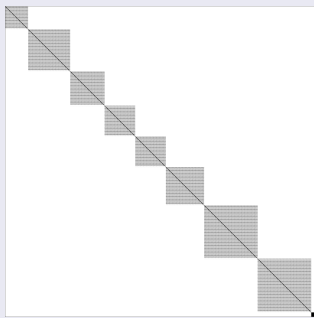# Radial discretisation – spectral multi-domain

Characteristics

- tridiagonal block matrix
  - good parallelisation

Illustration

- **Model**: ESTER
- **Resolution**: 10150×10150
  - $N_r =$
    $(30, 55, 45, 40, 40, 50, 70, 70, 30)$
  - $N_\theta = 5$
- **Fill factor**: 25.4%

Matrix

Typical numerical resolutions

- polytropes: $N_r = 60$, $N_\theta = 40$
- SCF: $N_r = 1601$, $N_\theta = 10$ to 50
- **Note**: $\ell_{\max} \simeq 2N_\theta$

Numerical cost for adiabatic calculations in ESTER models

N_r	N_θ	Memory (in Gb)	Time (in min)	Num. proc.
400	10	0.5	0.16	2
400	15	1.1	0.33	2
400	20	1.9	0.65	2
400	30	4.2	1.6	2
400	40	7.4	3.3	2
400	100	$\sim$70	24	25

Numerical cost for non-adiabatic calculations in ESTER models

N_r	N_θ	Memory (in Gb)	Time (in min)	Num. proc.
400	10	3.5		
400	15	7.9		
400	20	13.4	5	4
400	29	28.0	10	8
400	40	52.7	22	8
400	50	82.3	26	16

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Tests and precision of the method

Polytrope

- Comparison with Christensen-Dalsgaard and Mullan (1994) ($\Omega = 0$): $\Delta\omega/\omega \sim 10^{-7}$
- Comparison with Lignières et al. (2006): $\Delta\omega/\omega \sim 10^{-7}$
- Comparison with Saio (1981) for small Ω
- Variational principle: $\Delta\omega/\omega \sim 10^{-7}$ when $N = 3$ and $\Delta\omega/\omega \sim 10^{-5}$ when $N = 1.5$
- Numerically: $\Delta\omega/\omega \gtrsim 10^{-10}$
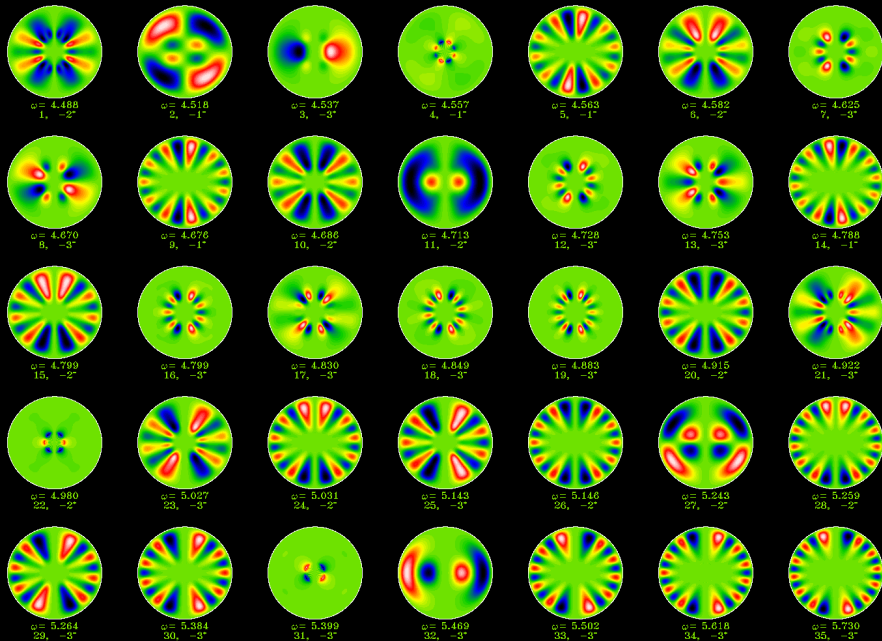- used to validate the ACOR, another 2D pulsation code (Ouazzani et al. 2012)

SCF

- Variational principle: $\Delta\omega/\omega \sim 10^{-4}$ à 10^{-3}
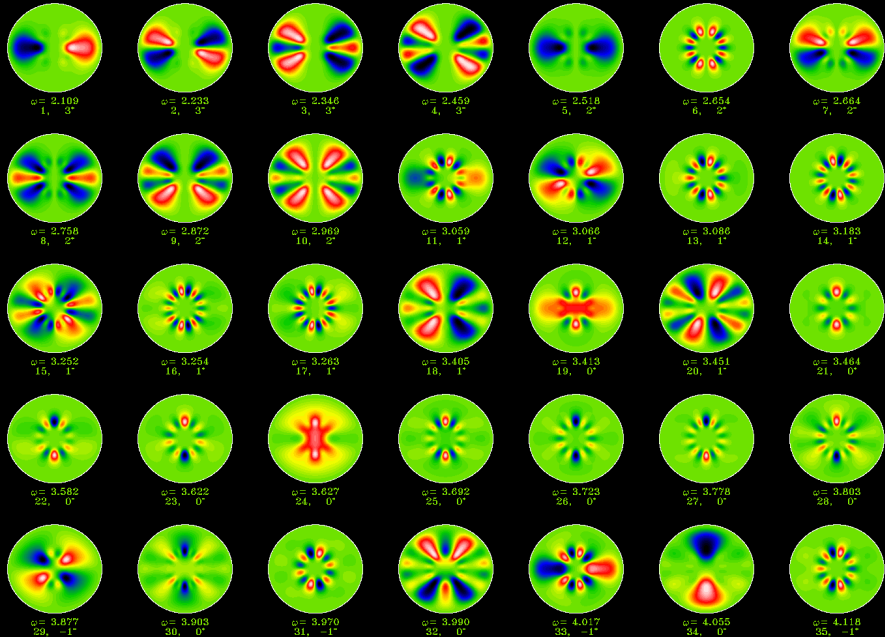- Numerically: $\Delta\omega/\omega \sim 10^{-5}$ à 10^{-4}

Tests and precision of the method – ESTER models
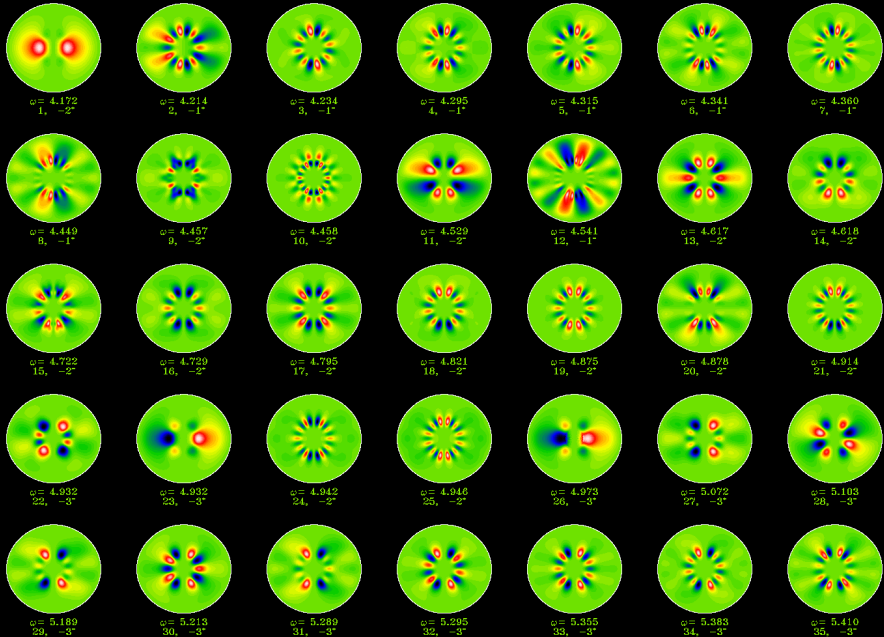

Estimated accuracy

- frequencies:
    - analytical EOS: 10^{-8} to 10^{-7}
    - tabulated EOS: $\sim 10^{-4}$
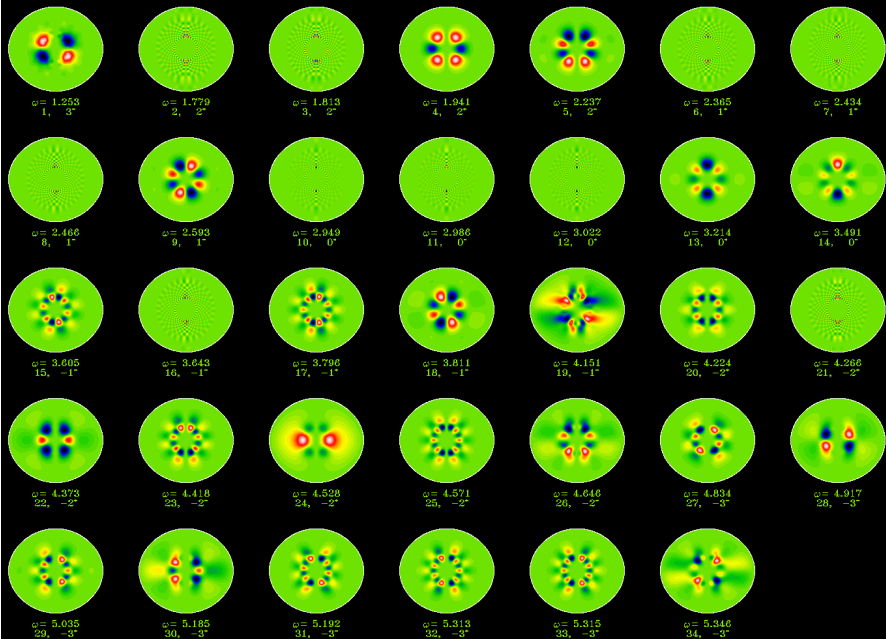- excitation/damping rates: 10^{-2} to 10^{-1}

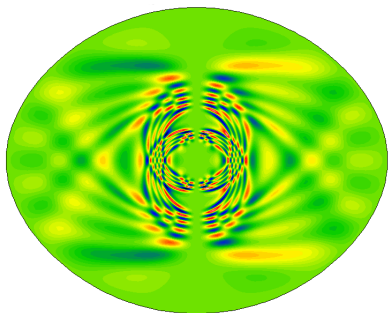$\Omega = 0.4\ \Omega k$

$\Omega = 0.5\ \Omega k$

$\Omega = 0.5\ \Omega k$

$\Omega = 0.6\,\Omega k$

Rosette modes

$2M_{\odot}$ $\Omega=0.7\Omega_{\kappa}$ $\alpha=0.0$
$14.2\mu Hz$ $m=3$

(Reese, 2013)

- first discovered by Ballot et al. (2011) using the TOP code
- further studied by Takata & Saio (2013, 2014, 2014b)