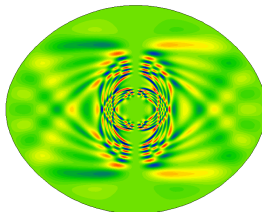


# 2D oscillation computations in rapidly rotating stars with the TOP code

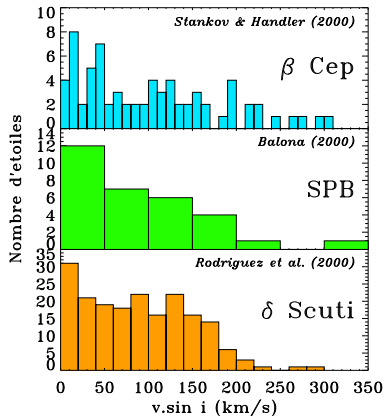
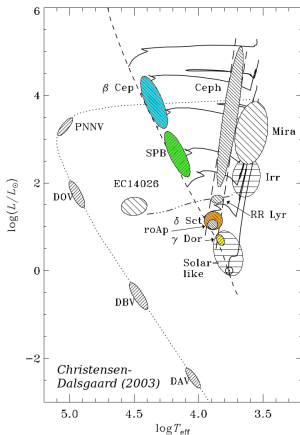
D. R. Reese

LESIA, Paris Observatory

November 29, 2018



# Scientific context

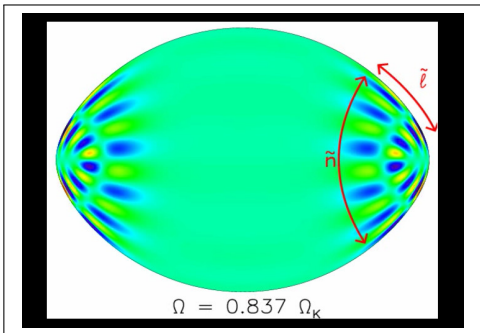


- seismic interpretation of rapidly rotating stars

# Scientific context

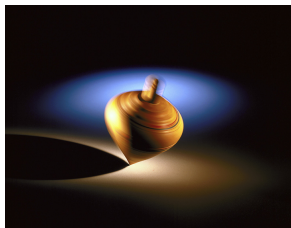
## Effects of rapid rotation

- centrifugal deformation
- Coriolis force
- significant distortion of pulsation modes
- need for a 2D numerical approach



# The TOP code

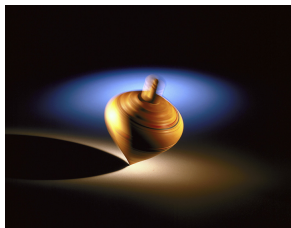
- TOP = Two-dimensional Oscillation Program
- top = “toupie” (in French)



<http://johnmannphoto.com/blog/?p=103>

# The TOP code

- TOP = Two-dimensional Oscillation Program
- top = “toupie” (in French)



<http://johnmannphoto.com/blog/?p=103>

- initially started writing the code in 2007-2009 during first postdoc in Sheffield
  - numerical method based on Lignières et al. (2006)
  - borrowed parts from LSB (= Linear Solver-Builder)
- multi-domain version 2010-2011 (with J. Ballot)
- non-adiabatic version 2012-2013 (with M.-A. Dupret)
- B. Putigny unified multiple versions, added a python interface, and started redoing the script language (~2013-present)

# The TOP code

## Basic characteristics

- Fortran 90 code
- Perl code for interpreting pulsation equations in script file
  - this produces Fortran code, prior to compilation
  - may be replaced by a newer interpreter in C++ & other language

Script file with equations



Pre-processing

Fortran source code



Compilation

Executable program

# The TOP code

## Current script

```

eq_cesam_all_lagrange_avg - /home/dreese/TOP/real2D/models/cesam/
File Edit Search Preferences Shell Macro Windows Help
/home/dreese/TOP/real2D/models/cesam/eq_cesam_all_lagrange_avg byte 0 of 13087 L: 1 C: 0
11 input gridfile a256
12 input inputlist a256
13
14 eqlist eqd_P eqEr eqSt eqPhi eqPhiP eqSp eqPhie eqPhieP
15 varlist dP_P Er Et Phi PhiP Rp Phie PhieP
16
17 suppress PhiP PhieP
18
19 lvar Er abs(m)+iparity
20 lvar Et abs(m)+iparity
21 lvar dP_P abs(m)+iparity
22 lvar Phi abs(m)+iparity
23 lvar PhiP abs(m)+iparity
24 lvar Phie abs(m)+iparity
25 lvar PhieP abs(m)+iparity
26 lvar Rp abs(m)+l-iparity
27
28 leq eqEr abs(m)+iparity
29 leq eqSt abs(m)+iparity
30 leq eqd_P abs(m)+iparity
31 leq eqPhi abs(m)+iparity
32 leq eqPhiP abs(m)+iparity
33 leq eqPhie abs(m)+iparity
34 leq eqPhieP abs(m)+iparity
35 leq eqRp abs(m)+l-iparity
36
37 -----
38 instruction lmax = maxval(lvar)
39 instruction call initialisation(nr,nr,m,lres,lmax) # this initialises
40 instruction call init_avg(dmat%derivate(1,1,0),dmat%lborder(0),dmat%lborder(
41 #
42 equation eqd_P
43
44 sub rtt w0 lllm_a(r_usap*roz*r_s/Gamma1,$a,$leg,$lvar) dP_P
45 sub rtt w0 lllm_a(rota,$a,$leg,$lvar) Er
46 term s w0 2d0 Er
47 term rt w0 -dble($lvar*$j1)*($lvar*$j1+1) Et
48
49 termb t nr w0 ldo Er^-1(l)
50 termb t nr w0 -dble($lvar*$j1) Et^-1(l)
51 -----
52 equation eqEr
53
54 sub rtt w2 lllm_a(r_s/roz**2,$a,$leg,$lvar) Er
55 sub rtt w1 lllm_a(2d0*m*Rot**2,r_s/roz**2,$a,$leg,$lvar) Er
56 sub rtt w0 lllm_a(m**2*Rot**2*r_s/roz**2,$a,$leg,$lvar) Er
57 sub rtt w2 lllm_a(rrt/roz,$a,$leg,$lvar) Et
58 sub rtt w1 lllm_a(2d0*m*Rot**2*rrt/roz,$a,$leg,$lvar) Et

```

## New script

```

cesam1D - /home/dreese/TOP/Bertrand/top/parser/examples/
File Edit Search Preferences Shell Macro Windows Help
/home/dreese/TOP/Bertrand/top/parser/examples/cesam1D byte 0 of 1988 L: 1 C: 0
1 input double mass
2 input double Rots
3 input double age
4 input string modelfile
5 input string gridfile
6 input int part_model
7 input string grid_type
8 input double C0
9 input double C1
10 input double C2
11 input double C3
12
13 var dP_P, (Er, Et), PhiP, Phi
14
15 field pm, g_m, r, rhom, dg_m, rhom_s
16 scalar Gamma1, Lambda
17
18 in
19
20 -----
21 equation eqd_P:
22 lh*(lh-1) * Et =
23 avg(r/Gamma1) * dP_P +
24 avg(r) * Er +
25 2 * Er
26 with (r=1)
27 dr(Er, -1) = lh * dr(Et, -1)
28 at r = 0
29
30 -----
31 equation eqEr:
32
33 PhiP =
34 fp^2 * Er +
35 avg(-pm/rhom) * dP_P +
36 avg(g_m*(1.0-1.0/Gamma1)) * dP_P +
37 avg(-g_m) * Er +
38 avg(-dg_m) * Er
39 with (r=1)
40 dr(dP_P, -1) = 0 at r = 1
41 # this is equivalent to setting delta P/P_0 = 0 on the edge:
42 # termbs s nr w0 ldo dP_P--1(nr)
43
44 -----
45 equation eqSt:
46
47 0 =
48 fp^2 * r * dr(Et, -1) -

```

# The TOP code

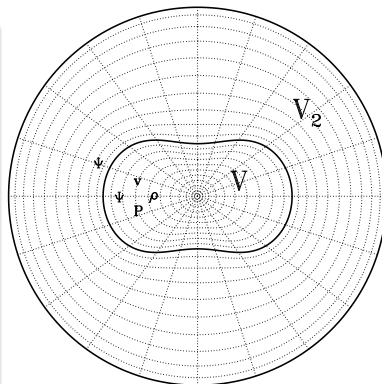
## Numerical aspects and parallelisation

- TOP relies on BLAS and LAPACK for most of the heavy computations
  - good optimisation on most (super-)computers
  - provides OpenMP type parallelisation
- experimented with ScaLAPACK library
  - provides MPI type parallelisation
  - may allow solving 3D problems (by increasing available RAM)



# Numerical approach

- 2D numerical approach
- Angular discretisation: spherical harmonic
- Radial discretisation:
  - polytrope: Chebyshev
  - realistic model: FD or splines
- Uses a suitable coordinate system  $(\zeta, \theta, \phi)$  (cf. Bonazzola et al., 1998)



$$[\text{System of equations}] \Rightarrow Av = \lambda Bv$$

# Method

1. Find explicit equations in spheroidal coordinates

Continuity equation

Euler's equation

Adiabatic relation

Poisson's equation

# Method

1. Find explicit equations in spheroidal coordinates

2. Express unknowns using spherical harmonics

For example: 
$$\Phi(\zeta, \theta, \varphi) = \sum_{\ell=|m|}^{\ell_{\max}} \Phi_m^{\ell}(\zeta) Y_{\ell}^m(\theta, \varphi)$$

# Method

1. Find explicit equations in spheroidal coordinates

3. Project equations on spherical harmonic basis

2. Express unknowns using spherical harmonics

For example: 
$$\iint_{4\pi} \{Y_\ell^m\}^* \{\text{Continuity equation}\} d\Omega$$

# Method

**1.** Find explicit equations in spheroidal coordinates

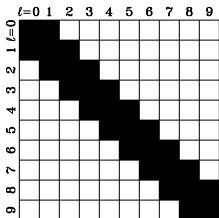
**3.** Project equations on spherical harmonic basis

**2.** Express unknowns using spherical harmonics

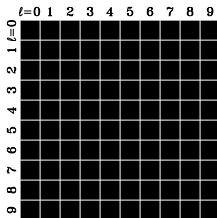
**4.** Carry out radial discretisation (Chebyshev, FD, splines)

*Generalised eigenvalue problem:  $Av = \lambda Bv$*

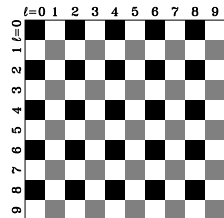
# Horizontal discretisation



**Only Coriolis**



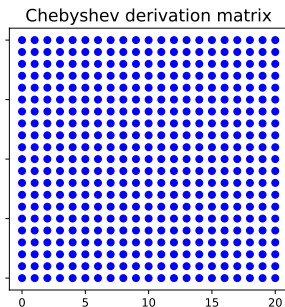
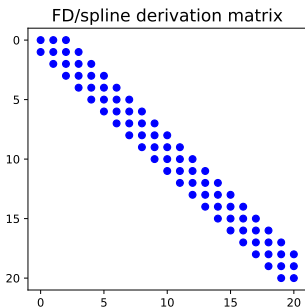
**Centrifugal def.**



**Equat. symmetry**

- spectral convergence with spherical harmonics
- problem couples all spherical harmonics of same parity

# Radial discretisation



Discretisation	Convergence	Grid
FD/splines	algebraic	flexible
Chebyshev polynomials	exponential	fixed

# Radial discretisation – Chebyshev polynomials

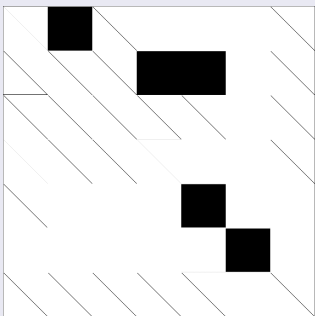
## Characteristics

- construct & factorise full matrix
  - good parallelisation

## Illustration

- **Model:** polytrope
- **Resolution:**  $5670 \times 5670$ 
  - $N_r = 81$
  - $N_\theta = 10$
- **Fill factor:** 10.6 %

## Matrix







# Matrix construction

- the order of the equations and the variables are set by the user
  - when dealing with FD/splines, group  $\ell$  values together to obtain banded matrix
  - fine-tune ordering to reduce number of bands

# Solving the eigenvalue problem

## Arnoldi-Chebyshev algorithm

- iterative procedure in which original matrix is approximated by a smaller matrix obtained by successive iterations of:  $Av$  starting with some initial vector  $v_0$

# Solving the eigenvalue problem

## Arnoldi-Chebyshev algorithm

- iterative procedure in which original matrix is approximated by a smaller matrix obtained by successive iterations of:  $Av$  starting with some initial vector  $v_0$

## Spectral transformation

$$Av = \lambda Bv \Leftrightarrow (A - \sigma B)^{-1} Bv = \mu v \quad \text{where} \quad \lambda = \sigma + \frac{1}{\mu}$$

- when targeting eigenvalues close to  $\sigma$ , we need to solve  $(A - \sigma B)X = Y$
- it is therefore necessary to construct and factorise  $A - \sigma B$

# Polynomial eigenvalue problem

$$\sum_{i=0}^n \lambda^i A_i v = 0 \quad \iff \quad \mathcal{A}x = \lambda \mathcal{B}x \quad \text{where}$$

$$\mathcal{A} = \begin{bmatrix} A_0 & \cdot & \cdot & \cdot \\ \cdot & I_d & \cdot & \cdot \\ \cdot & \cdot & \ddots & \cdot \\ \cdot & \cdot & \cdot & I_d \end{bmatrix}, \quad \mathcal{B} = \begin{bmatrix} -A_1 & -A_2 & \cdots & -A_n \\ I_d & \cdot & \cdot & \cdot \\ \cdot & \ddots & \cdot & \cdot \\ \cdot & \cdot & I_d & \cdot \end{bmatrix}, \quad x = \begin{bmatrix} v \\ \lambda v \\ \vdots \\ \lambda^{n-1} v \end{bmatrix}$$

## Solving $(\mathcal{A} - \sigma \mathcal{B})X = Y$

- 1  $X = [x_0 \dots x_{n-1}]^T, \quad Y = [y_0 \dots y_{n-1}]^T$
- 2 By induction, let us define  $(w_i)_{i \in [1, n-1]}$ :  
 $w_1 = \sigma y_1, \quad w_{i+1} = \sigma(y_{i+1} + w_i)$
- 3 Solve:  $x_0 = \left(\sum_{i=0}^n \sigma^i A_i\right)^{-1} \left(y_0 - \sum_{i=1}^{n-1} A_{i+1} w_i\right)$
- 4 By induction:  $x_{i+1} = y_{i+1} + \sigma x_i$

# The multi-domain approach

- **assumption:** only consecutive domains are coupled  
 ⇒ tridiagonal block matrix

$$\begin{bmatrix} A_{11} & A_{12} & & & \\ A_{21} & A_{22} & A_{23} & & \\ & & \ddots & A_{n-1,n} & \\ & & & A_{n,n-1} & A_{n,n} \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix} = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix}$$

## Solving this system

- use of Gauss' pivot to eliminate  $A_{i+1,i}$  and  $A_{i,i+1}$
- one should not forget that matrix multiplication is not commutative

## "Factorisation"

$$\tilde{A}_{11} = A_{11} \quad \tilde{A}_{i+1,i+1} = A_{i+1,i+1} - A_{i+1,i} \tilde{A}_{i,i}^{-1} A_{i,i+1}$$

## Downward sweep

$$\tilde{Y}_1 = Y_1 \quad \tilde{Y}_{i+1} = Y_{i+1} - A_{i+1,i} \tilde{A}_{i,i}^{-1} \tilde{Y}_i$$

## Upward sweep

$$X_n = \tilde{A}_{n,n}^{-1} \tilde{Y}_n \quad X_{i-1} = \tilde{A}_{i-1,i-1}^{-1} \left( \tilde{Y}_{i-1} - A_{i-1,i} \tilde{X}_i \right)$$

# Radial discretisation – spectral multi-domain

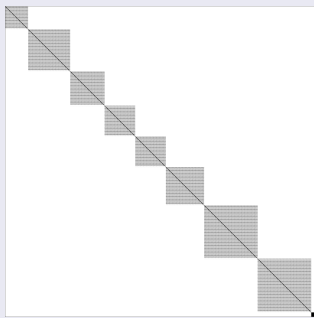
## Characteristics

- tridiagonal block matrix
  - good parallelisation

## Illustration

- **Model:** ESTER
- **Resolution:**  $10150 \times 10150$ 
  - $N_r =$   
(30, 55, 45, 40, 40, 50, 70, 70, 30)
  - $N_\theta = 5$
- **Fill factor:** 25.4 %

## Matrix





# Typical numerical resolutions

- polytropes:  $N_r = 60$ ,  $N_\theta = 40$
- SCF:  $N_r = 1601$ ,  $N_\theta = 10$  to  $50$
- **Note:**  $\ell_{\max} \simeq 2N_\theta$

## Numerical cost for adiabatic calculations in ESTER models

$N_r$	$N_\theta$	Memory (in Gb)	Time (in min)	Num. proc.
400	10	0.5	0.16	2
400	15	1.1	0.33	2
400	20	1.9	0.65	2
400	30	4.2	1.6	2
400	40	7.4	3.3	2
400	100	~70	24	25

## Numerical cost for non-adiabatic calculations in ESTER models

$N_r$	$N_\theta$	Memory (in Gb)	Time (in min)	Num. proc.
400	10	3.5		
400	15	7.9		
400	20	13.4	5	4
400	29	28.0	10	8
400	40	52.7	22	8
400	50	82.3	26	16

# Tests and precision of the method

## Polytrope

- Comparison with Christensen-Dalsgaard and Mullan (1994) ( $\Omega = 0$ ):  $\Delta\omega/\omega \sim 10^{-7}$
- Comparison with Lignières et al. (2006):  $\Delta\omega/\omega \sim 10^{-7}$
- Comparison with Saio (1981) for small  $\Omega$
- Variational principle:  $\Delta\omega/\omega \sim 10^{-7}$  when  $N = 3$  and  $\Delta\omega/\omega \sim 10^{-5}$  when  $N = 1.5$
- Numerically:  $\Delta\omega/\omega \gtrsim 10^{-10}$
- used to validate the ACOR, another 2D pulsation code (Ouazzani et al. 2012)

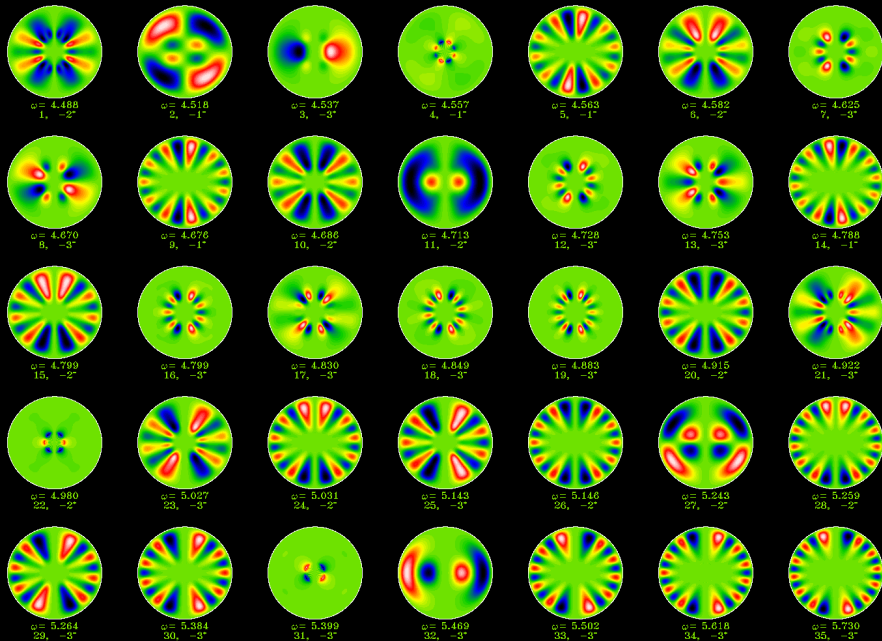
## SCF

- Variational principle:  $\Delta\omega/\omega \sim 10^{-4}$  à  $10^{-3}$
- Numerically:  $\Delta\omega/\omega \sim 10^{-5}$  à  $10^{-4}$

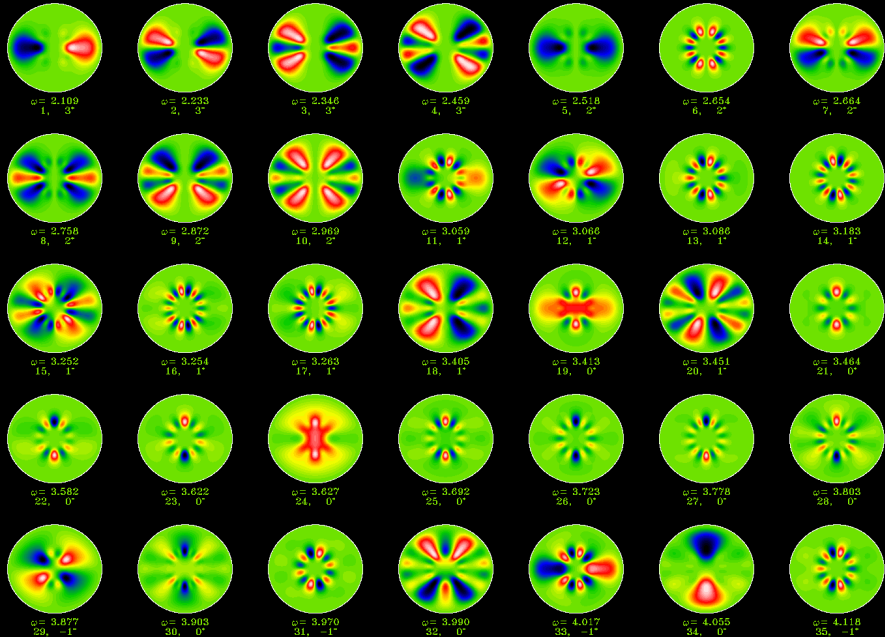
# Tests and precision of the method – ESTER models

## Estimated accuracy

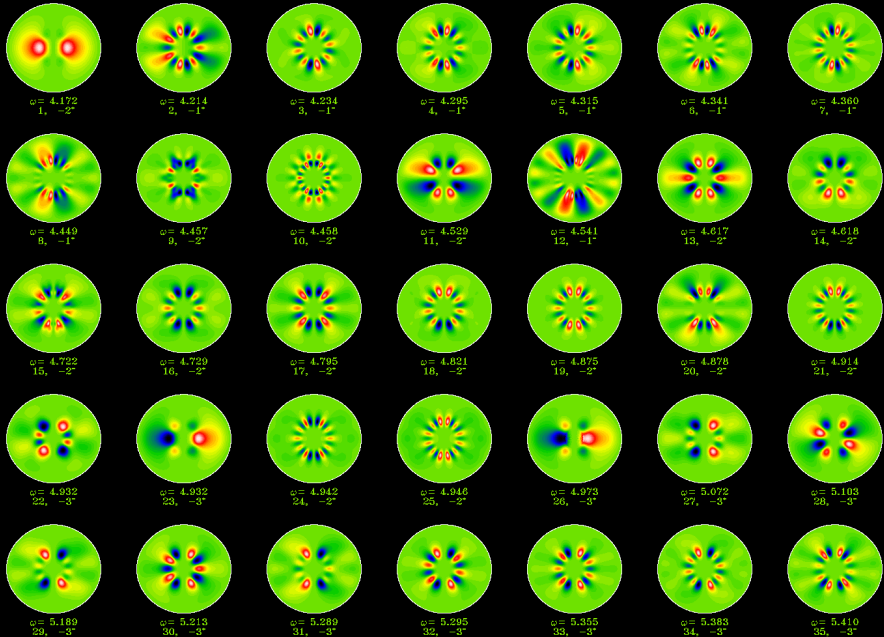
- frequencies:
  - analytical EOS:  $10^{-8}$  to  $10^{-7}$
  - tabulated EOS:  $\sim 10^{-4}$
- excitation/damping rates:  $10^{-2}$  to  $10^{-1}$



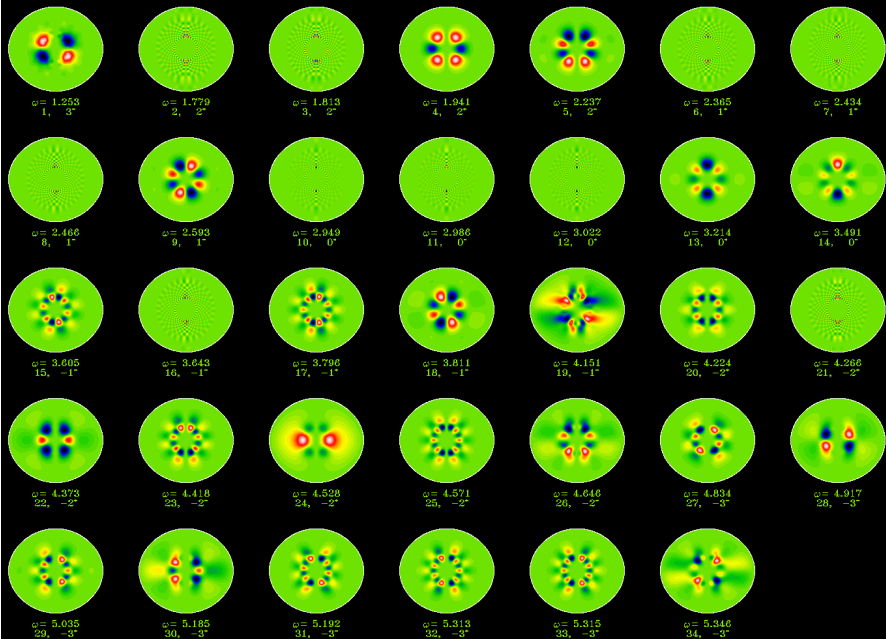
$$\Omega = 0.4 \Omega_k$$



$$\Omega = 0.5 \Omega_k$$



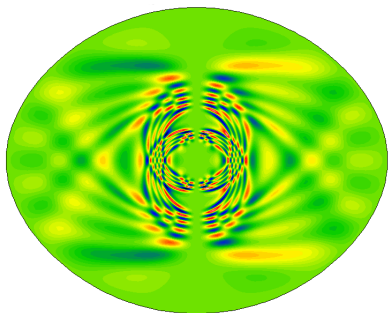
$$\Omega = 0.5 \Omega_k$$



$$\Omega = 0.6 \Omega_k$$



# Rosette modes



$$2M_{\odot} \quad \Omega = 0.7\Omega_{\text{K}} \quad \alpha = 0.0 \\ 14.2\mu\text{Hz} \quad m=3$$

(Reese, 2013)

- first discovered by Ballot et al. (2011) using the TOP code
- further studied by Takata & Saio (2013, 2014, 2014b)